MULTIPLE-SPEED POWER TRANSMISSION FOR MOTOR VEHICLES

BACKGROUND OF THE INVENTION

This invention relates to the field of automatic 5 transmissions for motor vehicles. More particularly, the invention pertains to the kinematic arrangement of planetary gearing, clutches, brakes, and overrunning couplings for such transmissions.

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Minimizing the package size of a geared automatic transmission for motor vehicles, its lateral dimensions and particularly its axial dimensions, has long been an objective in the automotive industry. Realizing this goal has become 15 more difficult because of the need for transmissions to provide a continually increasing number of forward gear ratios and a need for non-synchronous shifting among the gear ratios. Automatic transmissions having five and six forward gear ratios are replacing current transmissions having four and five forward gear ratios.

In order to minimize the axial length of an automotive transmission, the number of friction clutches and brakes is minimized. It has become conventional to provide non-synchronous gear ratio changes, especially among the lower gears, by providing a one-way coupling in parallel with a hydraulically actuated friction clutch or brake. However, a one-way coupling requires additional space along the axis of the transmission. Its presence also adds to assembly time, material cost, and weight.

In addition to minimizing the package size of automatic transmissions, it is important also to minimize the rotational speed of the pinion gears, which are supported on a carrier of the planetary gear units within the transmission.

Excessive planet pinion gear speed can adversely affect the service life of the bearings on which the planet pinions are supported for rotation on the carrier. It is not uncommon that the rotational speed of planet pinions of certain gear units be five to seven times the engine speed.

SUMMARY OF THE INVENTION

It is an advantage of this invention that the

rotational speed of the planet pinion gears is relatively low
in comparison to transmissions in the prior art, and that the
transmission is compact and has a minimal axial length.

Nearly ideal steps between gear ratios can be obtained with
reasonable "betas" in all gearsets. Beta is the ratio of the
diameter or number of teeth of a ring gear and a sun gear of
the same planetary gear unit.

It is another advantage of this invention that six forward speed ratios are produced with only five friction clutches and brakes and without need for an overrunning coupling. However, if non-synchronous gear ratio changes between first gear and second gear are desired, a one-way coupling can be provided in parallel with a friction brake.

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In realizing these advantages, a multiple-speed ratio automatic transmission according to this invention includes an input and output. A planetary gear system includes first, second and third planetary gear units, each gear unit having a sun gear, a ring gear, planet pinions meshing with the sun gear, planet pinions meshing with the ring gear, and a carrier rotatably supporting the planet pinions.

Certain gear unit components are functionally secured continually to other components, but some components are releasably secured to others. For example, the input is driveably connected to the sun gear of the first gear unit, the output is driveably connected to the carrier of the third gear unit, the ring gear of the second gear unit is driveably connected to the carrier of the third gear unit, the carrier of the second gear unit is driveably connected to ring gear of the third gear unit, and one of the carrier of the first gear unit and the ring gear of the first gear unit is secured against rotation.

A first brake releasably holds the sun gear of the second gear unit against rotation. A second brake releasably holds the carrier of the second gear unit and ring gear of the third gear unit against rotation. A first clutch driveably connects and disconnects the input and sun gear of the third gear unit. A second clutch driveably connects and disconnects the input and carrier of the second gear unit. A third clutch releases and driveably connects the other of the carrier and the ring gear of the first gear unit to the sun gear of the second gear unit.

Various objects and advantages of this invention will become apparent to those skilled in the art from the following detailed description of the preferred embodiment, when read in light of the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

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FIG. 1 is a schematic diagram of the kinematic arrangement of the gears, clutches, brakes, and couplings for a preferred embodiment of this invention;

FIG. 2 is a chart that shows the pattern of engagement and release of the clutches and brakes required to produce the various forward drive ratios and reverse drive ratio of the transmission of Figures 1 and 3;

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FIG. 3 is a schematic diagram of the kinematic arrangement of an alternate embodiment of the automatic transmission of this invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring now to the drawings, there is illustrated in Fig. 1 the kinematic arrangement of an automatic transmission according to the present invention. The torque converter 10 includes an impeller wheel 12 connected to the crankshaft 14 of an internal combustion engine, a bladed turbine wheel 16, and a bladed stator wheel 18. The impeller, stator and turbine wheels define a toroidal fluid flow circuit, whereby the impeller is hydrokinetically connected to the turbine. The stator 18 is supported rotatably on a stationary stator sleeve shaft 20, and an overrunning brake 22 anchors the stator to the shaft 20 to prevent rotation of the stator in a direction opposite the direction of rotation of the impeller, although free-wheeling motion in the opposite direction is permitted.

The torque converter assembly includes a lockup clutch 24 located within the torque converter impeller housing 25. The torque output side of lockup clutch 24 includes a damper 26 located between the impeller and the turbine shaft, which is the transmission input shaft 28. When clutch 24 is engaged, the turbine and impeller are mechanically connected; when clutch 24 is disengaged, they are hydrokinetically connected and mechanically disconnected. The damper absorbs transitory torque fluctuations associated with engagement of a

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brake 74 holds carrier 50 and ring gear 56 against rotation on the transmission case 70; carrier 50 and ring gear 56 are released for free, independent rotation upon disengagement of brake 74.

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hydraulically-actuated friction devices having sets of interleaved friction discs and spacer plates, the discs secured to one element of the clutch or brake, the spacer plates secured to another element of the clutch or brake. Hydraulic pressure forces the discs and plates into frictional contact and completes a drive connection between the components to which the elements of the clutch or brake are secured. When the pressure is vented from the device, the clutch or brake is disengaged and the components are free to rotate independently. U.S. Patent 4,943,921 describes and illustrates examples of hydraulically actuated friction clutches and brakes, and a one-way coupling that can be used in the transmission of this invention.

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If non-synchronous gear ratio changes between first gear and second gear are desired, a one-way coupling 78 can be provided in parallel with brake 74. Preferably coupling 78 provides a one-way drive connection between the case 70 and the mutually connected ring gear 56 and carrier 50. Coupling 78 produces a drive connection to the case 70 in first gear, and it overruns in all other gears. One-way coupling 78 includes an inner race 80 connected to drum 82, which is secured to ring gear 56 and carrier 50, an outer race 84 secured to case 70 against rotation, and a set of rollers 86 or sprags located between the races and adapted to complete a one-way drive connection between the races.

Ring gear 48 of the second gear unit and carrier 58 of the third gear unit are mutually driveably connected, and

they are connected also to output shaft 84. A differential mechanism (not shown), driveably connected to output 84, transmits power to the drive wheels of a vehicle, as described and illustrated in U.S. Patent 5,261,862.

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A gear selector lever, controlled by the vehicle operator to select the operating range of the transmission, is movable among positions where the various gear ratios are produced automatically and other positions where the gear ratios are produced manually. Operation of the kinematic components of the transmission is described next with reference to the state of the friction elements and the coupling corresponding to each of the gear ratios. Preferably, the states of the clutches and brakes are changed automatically in accordance with execution of a control algorithm by an electronic transmission controller.

FIG. 2 is a chart indicating the state of engagement and disengagement of the clutches and brakes corresponding to each of the gear ratios. In the chart, symbol "X" identifies an engaged friction clutch and friction brake. A blank indicates that the corresponding clutch and brake is disengaged or released.

When the transmission operates in the first gear ratio, forward clutch 64 is engaged and brake 74 is engaged, thereby holding ring gear 56 against rotation on the transmission casing 70. The first speed ratio is produced in the third gear unit 36 and the output is taken at carrier 58, 30 which drives output shaft 84.

An upshift to the second speed ratio results by maintaining forward clutch 64 engaged, by engaging brake 72, and releasing brake 74. Sun gear 54 of the third gear unit 36 is connected to input shaft 28. Sun gear 46 of the second

gear unit 34 is held against rotation on the housing 70, and the output is taken at carrier 58 and output shaft 84.

An upshift to the third speed ratio from the second speed ratio results upon disengagement of brake 72 and engagement of clutch 68, while maintaining the forward clutch 64 engaged. Sun gear 38 of the first gear unit 32 is driven directly from the input shaft 28, ring gear 40 is held against rotation; therefore, carrier 42 and sun gear 46 are underdriven in relation to the speed of shaft 28. Sun gear 54 of the third gear unit is driven through clutch 64 from the input shaft 28. Ring gear 56 is connected to carrier 50; therefore the mutually interconnected ring gear 48 and carrier 58 drive output shaft 84.

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A fourth forward speed ratio is produced by maintaining forward clutch 64 engaged, applying clutch 66, and releasing the other friction elements. Sun gear 54, and the mutually interconnected carrier 50-ring gear 56 subassembly are driven at the speed of input shaft 28 through clutches 64 and 66, respectively. Therefore the third gear unit 36 is locked-up and output shaft 84 is driven at the speed of shaft 28, a direct drive speed ratio.

The fifth speed ratio is produced upon engaging clutch 66 and clutch 68, and disengaging clutch 64. Carrier 42, the underdriven output of the first gear unit 32, drives sun gear 46 through clutch 68. Carrier 50 is driven at the speed of the input shaft 28 through clutch 66. Therefore, the output is taken at ring gear 48, carrier 58, and output shaft 84, an overdrive gear ratio.

The sixth forward speed ratio results when clutch 66 and brake 72 are engaged, and the other friction elements are disengaged. Carrier 50 is driven by input shaft 28 through

clutch 66, and sun gear 46 is held against rotation, thereby providing a torque reaction on the case 70. This action overdrives ring gear 48, carrier 58 and shaft 84 in comparison to the speed of input shaft 28.

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Reverse drive results by engaging clutch 68 and brake 74, and releasing the other friction elements. Carrier 42, the underdriven output of gear unit 32, underdrives sun gear 46 through clutch 68. The second gear unit 34, whose carrier 50 provides a torque reaction due to engagement of brake 74, further underdrives ring 48, carrier 58 and output 84 and reverses their direction of rotation in comparison to the speed and direction of the input shaft 28.

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In FIG. 3, the various components on the transmission are marked with the same reference numbers as corresponding components of FIG. 1. The first gear set 32' is a compound planetary gear unit including a sun gear 38, ring gear 40, carrier 42', and two sets of planetary pinions 88, 90 of equal size, supported on a carrier 42'. The first pinion set 88 is in continuous meshing engagement with sun gear 38; the second pinion set 90 is in continuous meshing engagement with ring gear 40 and with the first pinion set 88. Carrier 42' is secured to the case 70 against rotation.

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If non-synchronous gear ratio changes between first gear and second gear are desired, a one-way coupling 78 can be provided in parallel with brake 74. Preferably coupling 78 provides a one-way drive connection between the case 70 and the mutually connected ring gear 56 and carrier 50. Coupling 78 produces a drive connection to the case 70 in first gear and second gear, and it overruns in all other gears.

The description that follows describes operation of the kinematic arrangement of FIG. 3 for and each of the

forward and reverse gear ratios with reference to the schedule of FIG. 2.

When the transmission operates in the first gear ratio, forward clutch 64 is engaged and brake 74 is engaged, thereby holding ring gear 56 against rotation on the transmission casing 82. The first speed ratio is produced in the third gear unit 36 and the output is taken at carrier 58, which drives output shaft 84.

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An upshift to the second speed ratio results by maintaining forward clutch 64 engaged, engaging brake 72, and disengaging brake 74. Sun gear 54 of the third gear unit 36 is connected to input shaft 28. Sun gear 46 of the second gear unit 34 is held against rotation on the housing 70, and the output is taken at carrier 58 and output shaft 84.

An upshift to the third speed ratio from the second speed ratio results upon disengagement of brake 72 and engagement of clutch 68', while maintaining the forward clutch 64 engaged. Sun gear 38 of the first gear unit 32 is driven directly from the input shaft 28, carrier 42' is held against rotation; therefore, ring gear 40 and sun gear 46 are underdriven in relation to the speed of shaft 28. Sun gear 54 of the third gear unit is driven through clutch 64 from the input shaft 28. Ring gear 56 is connected to carrier 50; therefore the mutually interconnected ring gear 48 and carrier 58 drive output shaft 84.

Maintaining forward clutch 64 engaged, applying clutch 66, and releasing the other friction elements produces the fourth forward speed ratio. Sun gear 54 and the mutually interconnected carrier 50-ring gear 56 subassembly are driven at the speed of input shaft 28 through clutches 64 and 66, respectively. Therefore, the third gear unit 36 is locked-up

and output shaft 84 is driven at the speed of shaft 28, a direct drive speed ratio.

The fifth speed ratio is produced upon engaging clutch 66 and clutch 68', and disengaging clutch 64. Carrier 42' provides a torque reaction on the case 70. Ring gear 40, the underdriven output of the first gear unit 32, drives sun gear 46 through clutch 68. Carrier 50 is driven at the speed of the input shaft 28 through clutch 66. Therefore, the output is taken at ring gear 48, carrier 58, and output shaft 84, an overdrive gear ratio.

The sixth forward speed ratio results when clutch 66 and brake 72 are engaged, and the other friction elements are disengaged. Carrier 50 is driven by input shaft 28 through clutch 66, and sun gear 46 is held against rotation, thereby providing a torque reaction on the case 70. This action overdrives ring gear 48, carrier 58 and shaft 84 in comparison to the speed of input shaft 28.

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Reverse drive results by engaging clutch 68' and brake 70, and releasing the other friction elements. Carrier 42, the underdriven output of gear unit 32, underdrives sun gear 46 through clutch 68'. The second gear unit 34, whose carrier 50 provides a torque reaction due to engagement of brake 74, further underdrives ring 48, carrier 58 and output 84 and reverses their direction of rotation in comparison to the speed and direction of the input shaft 28.

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In accordance with the provisions of the patent statutes, the principle and mode of operation of this invention have been explained and illustrated in its preferred embodiment. However, it must be understood that this invention may be practiced otherwise than as specifically

explained and illustrated without departing from its spirit or scope.